

# Lonza

## Robotics and Automation Leader

### Job Description Summary

#### Leader Robotics and Automation

Today, Lonza is a global leader in life sciences operating across three continents. While we work in science, there's no magic formula to how we do it. Our greatest scientific solution is talented people working together, devising ideas that help businesses to help people. In exchange, we let our people own their careers. Their ideas, big and small, genuinely improve the world. And that's the kind of work we want to be part of.

We are currently looking for a Robotics & Automation Leader at our site in [Visp](#) to build up a strong team and bring Lonza to the next level of 21st century automation & robotics in the pharmaceutical industry.

#### Key responsibilities:

- Constantly challenge existing manual practices and watch out for best automation and robotics within Pharma and as well as other industries to get ideas for improvement of current practices
- Drive standardization and efficiency in QC
- Accountable for the implementation of lean lab at the Visp site
- Increase efficiency and digitalization of Quality processes in close collaboration Head digital transformation, global QMS and global IT

#### Key requirements:

- BSc/MSc in a scientific field
- English & German, both business fluent
- Vast Automation and Robotics experience

Every day, Lonza's products and services have a positive impact on millions of people. For us, this is not only a great privilege, but also a great responsibility. How we achieve our business results is just as important as the achievements themselves. At Lonza, we respect and protect our people and our environment. Any success we achieve is no success at all if not achieved ethically.

People come to Lonza for the challenge and creativity of solving complex problems and developing new ideas in life sciences. In return, we offer the satisfaction that comes with improving lives all around the world. The satisfaction that comes with making a meaningful difference.